## Claims:

- 1 1. A system for a magnetic head arm assembly (HAA) comprising:
- a head gimbal assembly (HGA) with an HGA mating portion;
- a flexible printed circuit (FPC) assembly with an FPC mating portion; and
- an actuator coil assembly with a first mating portion and a second mating portion;
- 5 wherein
- each of said HGA, said FPC assembly, and said actuator coil assembly being
- 7 manufactured independent of one another;
- said HGA mating portion is to be coupled to said actuator coil assembly first mating
- 9 portion; and
- said FPC mating portion is to be coupled to said actuator coil assembly second mating
- 11 portion.
- 1 2. The system of claim 1, wherein said actuator coil assembly first mating portion and
- 2 second mating portion each have substantially smooth interface surfaces, and wherein said HGA
- 3 mating portion and FPC mating portion each have substantially smooth interface surfaces.
- 1 3. The system of claim 2, wherein said actuator coil assembly first mating portion and
- 2 second mating portion each have substantially flat interface surfaces, and wherein said HGA
- mating portion and FPC mating portion each have substantially flat interface surfaces.

- 1 4. The system of claim 3, wherein said actuator coil assembly first mating portion is
- 2 recessed and contoured to interface said HGA mating portion and wherein said actuator coil
- 3 assembly second mating portion is contoured to interface said FPC mating portion.
- 1 5. The system of claim 3, wherein said HGA is a unimount HGA.
- 1 6. The system of claim 5, wherein at least one of said HGA, said FPC assembly, and said
- 2 actuator coil assembly is manufactured by injection molding.
- 1 7. The system of claim 6, wherein said unimount HGA includes a unimount baseplate
- 2 containing said HGA mating portion, a multi-piece loadbeam, a flex-suspension assembly (FSA)
- 3 trace, and a slider device.
- 1 8. The system of claim 7, wherein said FPC assembly includes a plastic bracket, a metal
- bracket containing said FPC mating portion, and a flexible printed circuit.
- 1 9. The system of claim 8, wherein said actuator coil assembly includes a coil and an
- 2 actuator body containing said first and second mating portions.
- 1 10. A method for manufacturing a magnetic head arm assembly (HAA) comprising:
- 2 providing a head gimbal assembly (HGA), said HGA having an HGA mating portion;
- providing a flexible printed circuit (FPC) assembly, said FPC having an FPC mating
- 4 portion;

- 5 providing an actuator coil assembly, said actuator coil assembly having a first mating
- 6 portion and a second mating portion, wherein each of said HGA, FPC assembly, and actuator
- 7 coil assembly is manufactured independently from each other;
- 8 coupling said HGA mating portion to said actuator coil assembly first mating portion;
- 9 and
- coupling said FPC mating portion to said actuator coil assembly second mating portion.
- 1 11. The method of claim 10, wherein said actuator coil assembly first mating portion and
- 2 second mating portion each have substantially smooth interface surfaces, and wherein said HGA
- mating portion and FPC mating portion each have substantially smooth interface surfaces.
- 1 12. The method of claim 11, wherein said actuator coil assembly first mating portion and
- 2 second mating portion each have substantially flat interface surfaces, and wherein said HGA
- 3 mating portion and FPC mating portion each have substantially flat interface surfaces.
- 1 13. The method of claim 12, wherein said actuator coil assembly first mating portion is
- 2 recessed and contoured to interface said HGA mating portion and wherein said actuator coil
- 3 assembly second mating portion is contoured to interface said FPC mating portion.
- 1 14. The method of claim 12, wherein at least one of said HGA, said FPC assembly, and said
- 2 actuator coil assembly is manufactured by injection molding.
- 1 15. The method of claim 14, wherein said HGA is a unimount HGA.



- 1 16. The method of claim 15, wherein said unimount HGA includes a unimount baseplate
- 2 containing said HGA mating portion, a multi-piece loadbeam, a flex-suspension assembly (FSA)
- 3 trace, and a slider device.
- 1 17. The method of claim 16, wherein said FPC assembly includes a plastic bracket, a metal
- 2 bracket containing said FPC mating portion, and a flexible printed circuit.
- 1 18. The method of claim 17, wherein said actuator coil assembly includes a coil and an
- 2 actuator body containing said first and second mating portions.
- 1 19. The method of claim 18, wherein said FPC is coupled to said actuator body by rivet
- 2 deformation.
- 1 20. The method of claim 18, wherein said FPC is coupled to said actuator body by adhesive
- 2 bonding.
- 1 21. The method of claim 18, wherein said FPC is coupled to said actuator body by solder
- 2 bonding.
- 1 22. The method of claim 18, wherein said coil is coupled to an FPC trace by solder bonding.
- 1 23. The method of claim 18, wherein said coil is coupled to an FPC trace by stitch bonding.

- 1 24. The method of claim 18, wherein said HGA assembly is coupled to said FPC assembly
- 2 by adhesive bonding.
- 1 25. The method of claim 18, wherein said HGA assembly is coupled to said FPC assembly
- 2 by rivet deformation.
- 1 26. The method of claim 18, wherein said HGA assembly is coupled to said FPC assembly
- 2 by screw mounting.
- 1 27. The method of claim 18, wherein said FSA trace is coupled to a bonding pad of said FPC
- 2 assembly by tape automated bonding (TAB).
- 1 28. The method of claim 18, wherein said FSA trace is coupled to a bonding pad of said FPC
- 2 assembly by anisotropic conductive film (ACF) bonding.
- 1 29. The method of claim 18, wherein said multi-piece loadbeam is coupled to said unimount
- 2 baseplate by laser welding.
- 1 30. The method of claim 18, wherein said FSA trace is coupled to said HGA assembly by
- 2 ultra-violet (UV) epoxy bonding.
- 1 31. The method of claim 18, wherein said FPC assembly is coupled to said metal bracket by
- 2 lamination.

- 1 32. The method of claim 18, wherein said FPC assembly is coupled to said plastic bracket by
- 2 pin insertion.
- 1 33. The method of claim 18, wherein said coil is coupled to said actuator body by epoxy.